



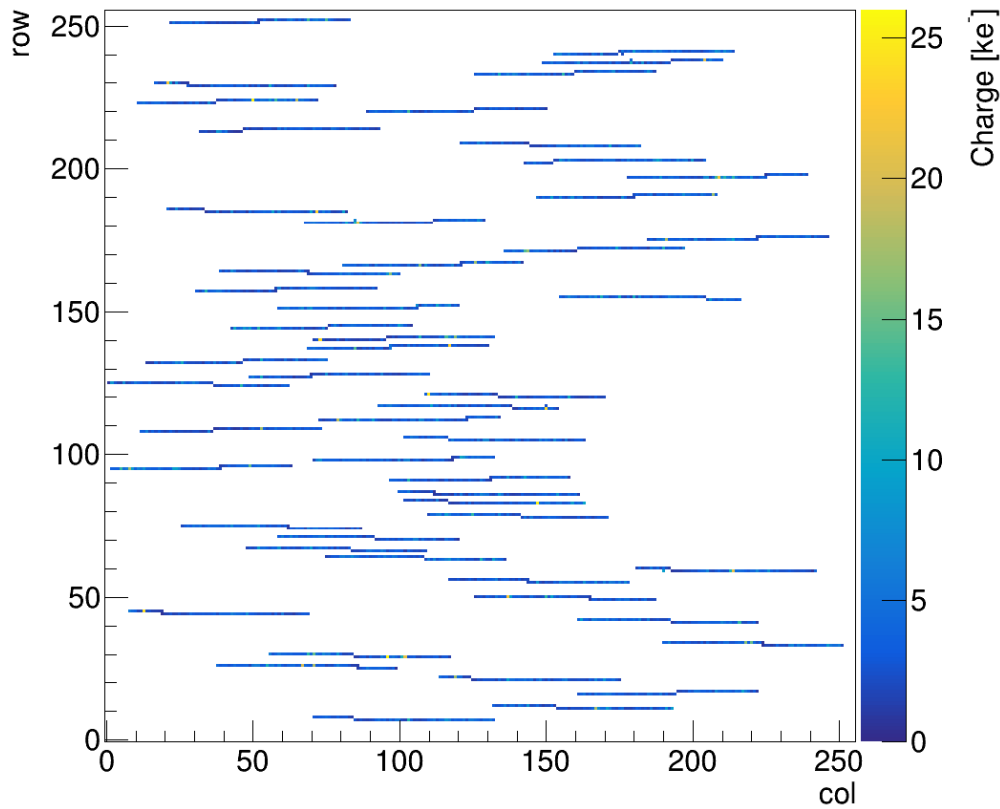
Weekly meeting

25 April 2019

Peter Bosch

Grazing angles

Run 31174
3D sensor
 $V_{\text{bias}} = 60\text{V}$
Angle = 85°
Long run



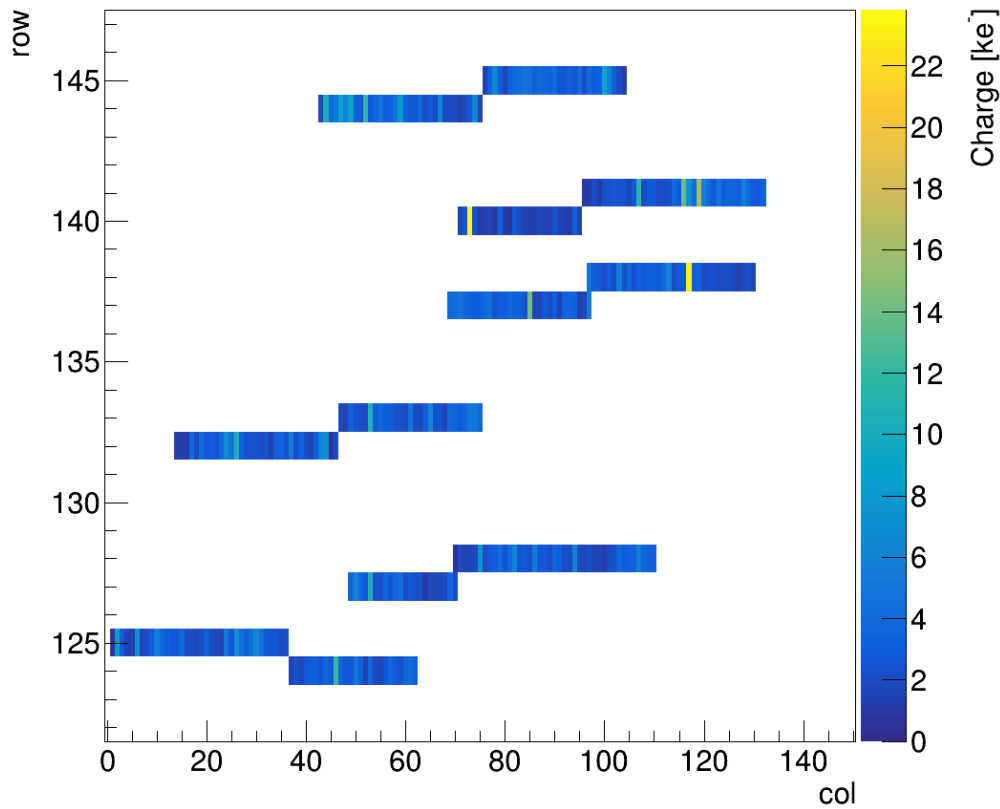
Look to grazing to determine height pillars

Double rows for field pillars

Around row crossing

Grazing angles

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3D sensor
 $V_{\text{bias}} = 60\text{V}$
Angle = 85°
Long run



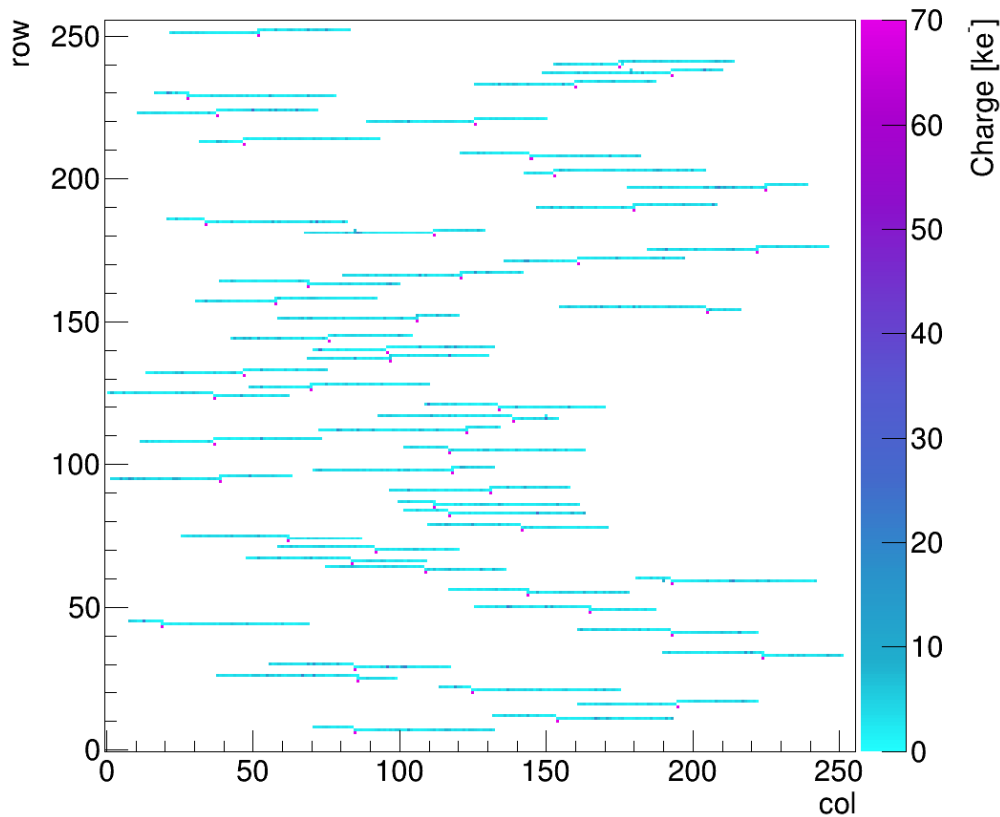
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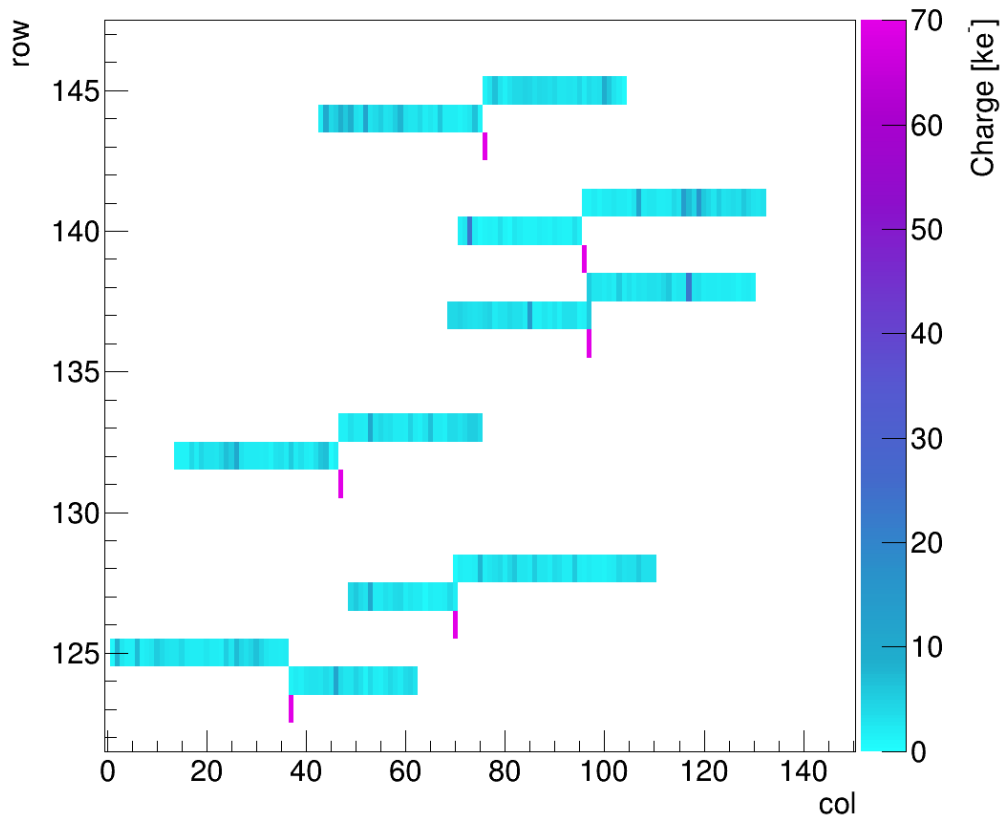
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Around row crossing

Purple: crossing point

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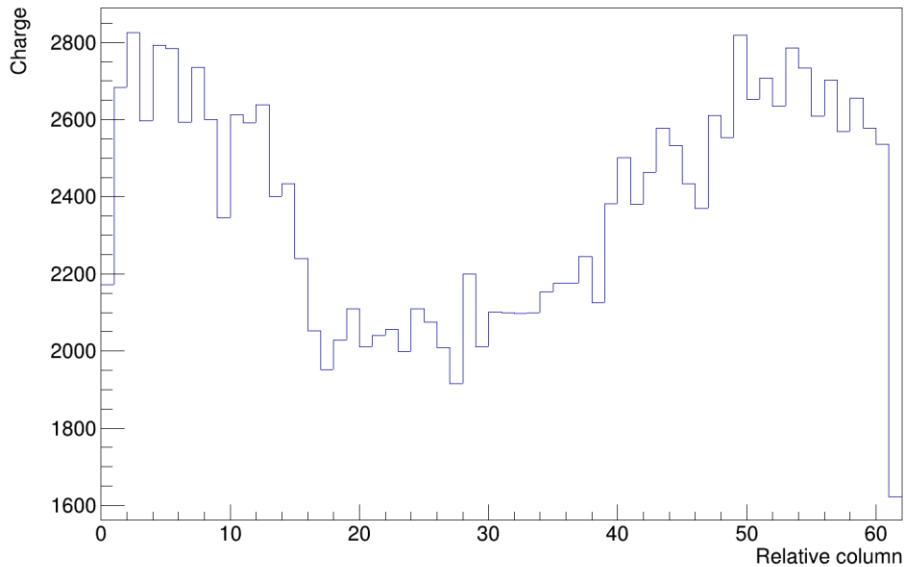
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Used whole tracks

Todo: only use 10 columns
before/after crossing

