



Weekly meeting

3 March 2019

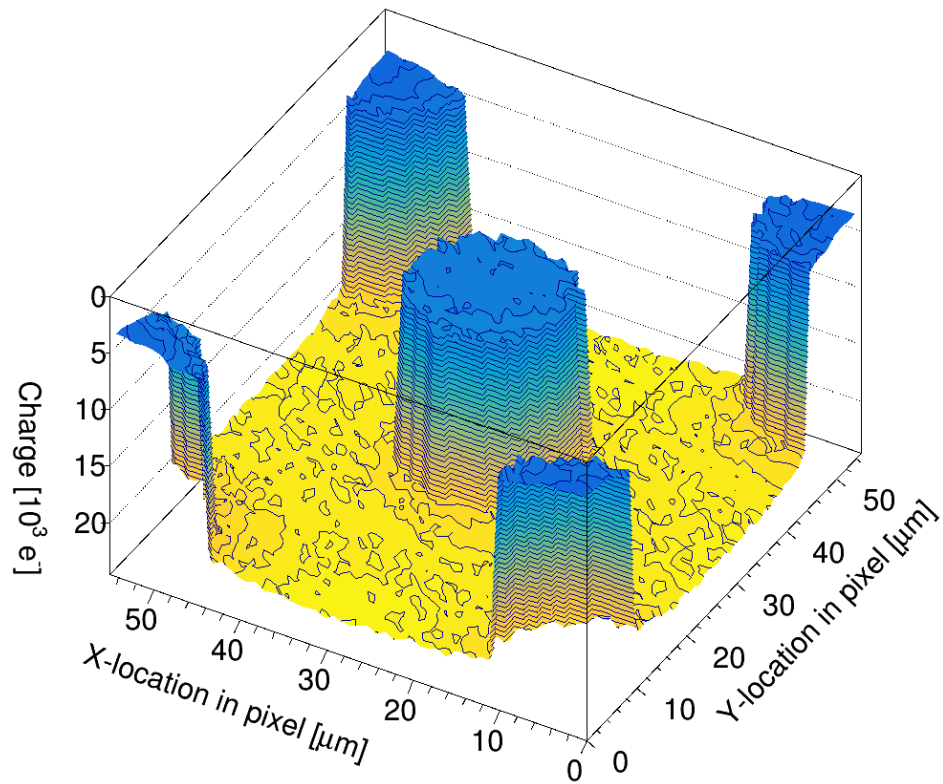
Peter Bosch

t0 offset

- Angle scan of 3D sensor
- Find correlation in time
- Use offset in Kepler
- Still no tracks...
- Use 2D scan

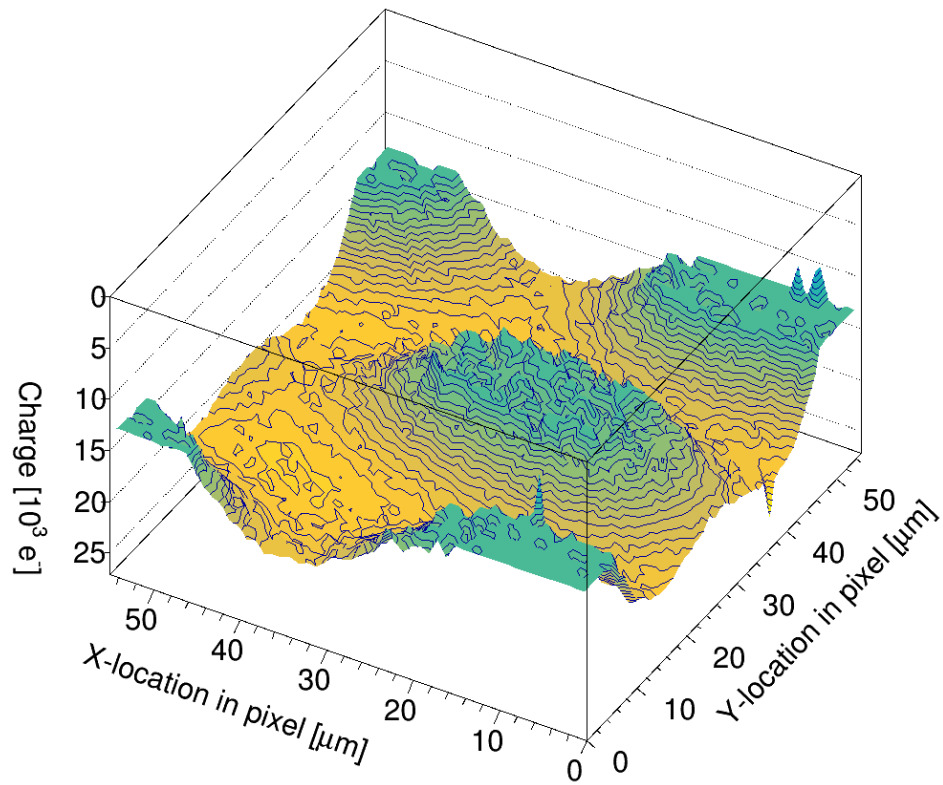
Charge map under angle

Run 31618
3D sensor
 $V_{\text{bias}} = 40\text{V}$
Angle = 0°
5 spills



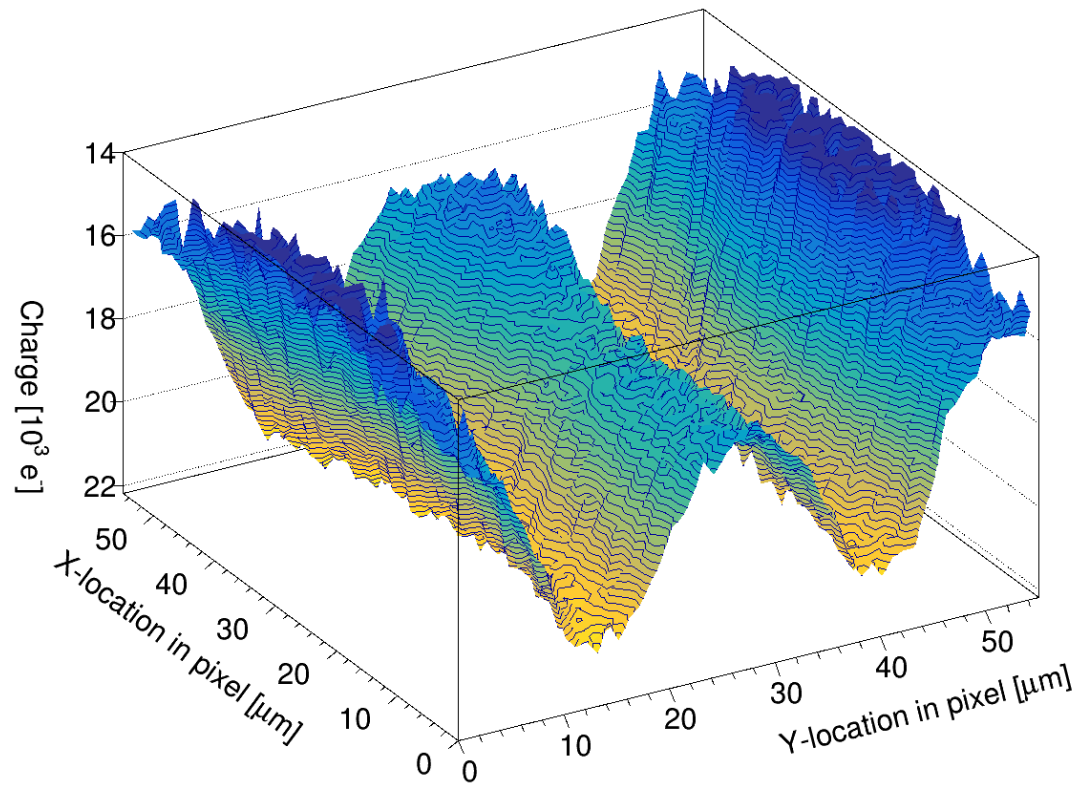
Charge map under angle

Run 31621
3D sensor
 $V_{\text{bias}} = 40\text{V}$
Angle = 9°
5 spills



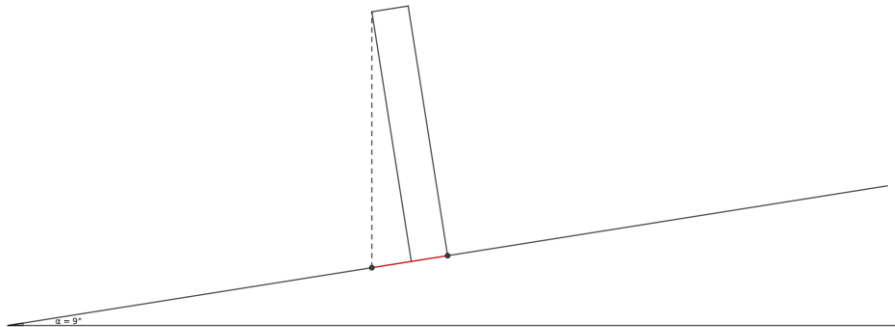
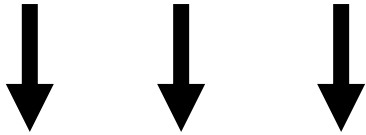
Charge map under angle

Run 31624
3D sensor
 $V_{\text{bias}} = 40\text{V}$
Angle = 15°
5 spills

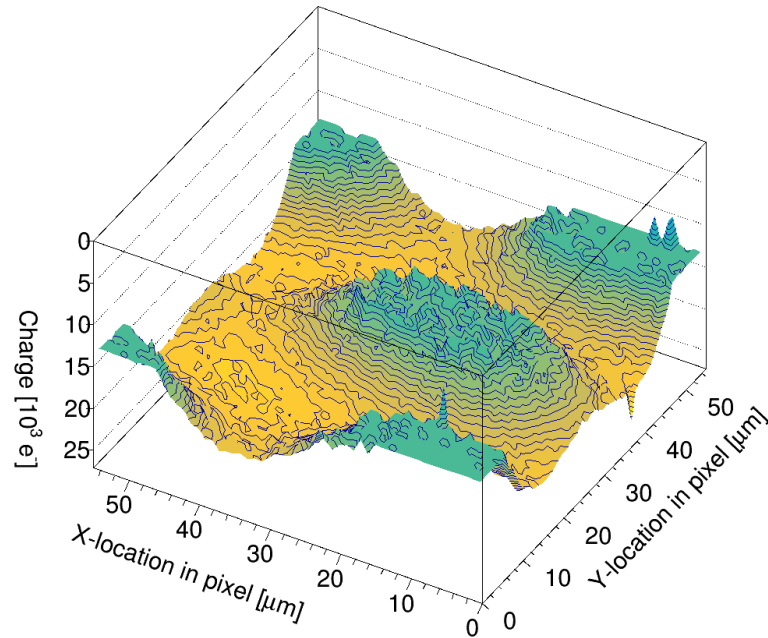


Charge map under angle

Run 31621
3D sensor
 $V_{\text{bias}} = 40\text{V}$
Angle = 9°
5 spills



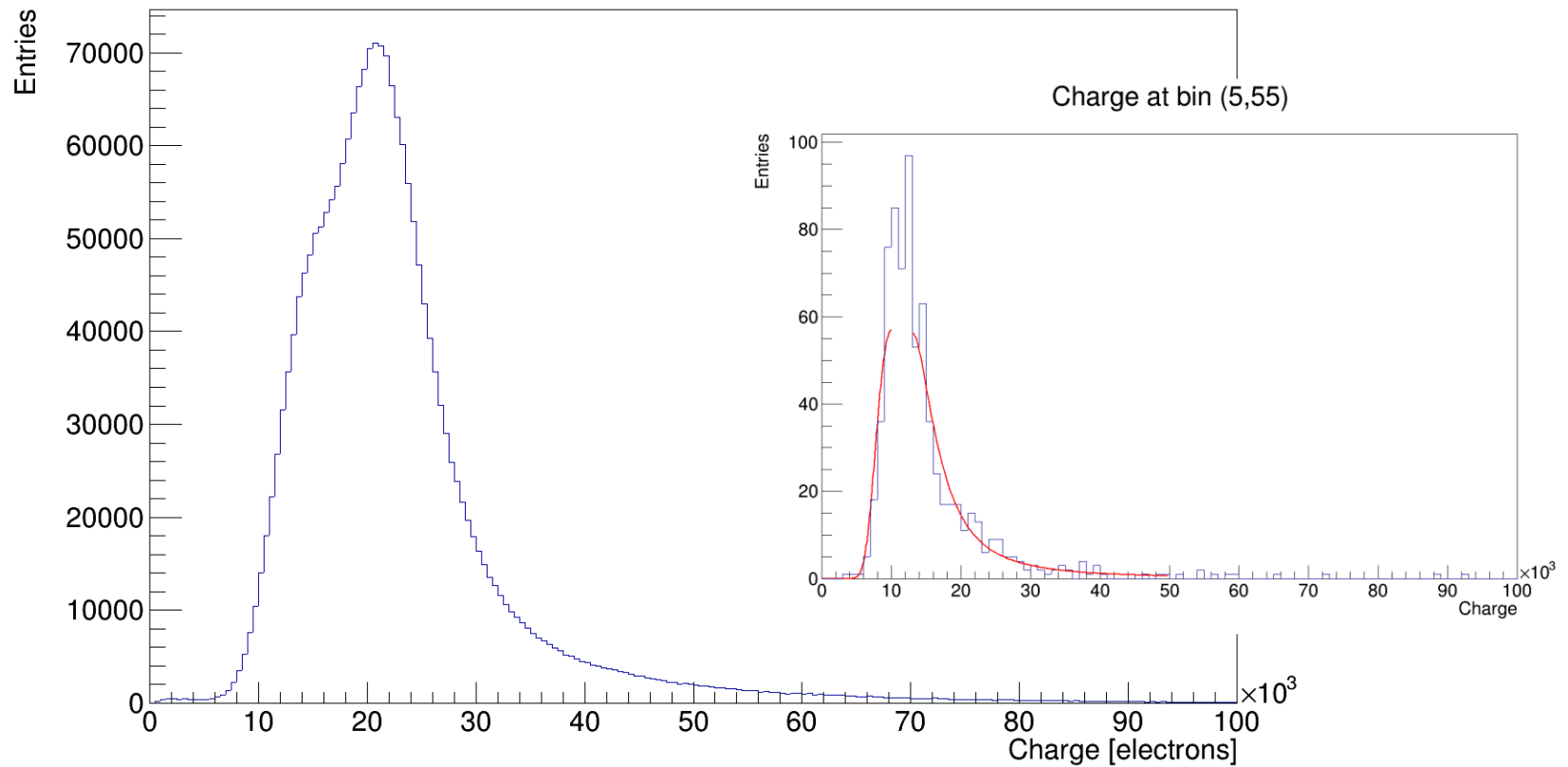
Red = width pillar 0° + height pillar * $\tan(\alpha)$
 $\approx 10 + 40 \mu\text{m}$ (20+40?)
 $\approx 50 \mu\text{m}$ (60?)



Charge map under angle

Run 31621
3D sensor
 $V_{\text{bias}} = 40\text{V}$
Angle = 9°
5 spills

Charge distribution for part 1



To continue

- Use single fit (?)
- Charge pillar -> projection of height?